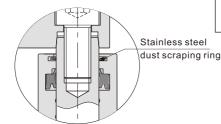


Rotary clamp cylinder——QCK Series

Compendium of QCK Series

Dustproof and welding slag out desigh

The front cover with stainless steel dust scraping ring, can keep the dust and welding slag out, and protect cylinder internal parts.



Two kinds of rod type

Taper type (with clamp arm)

Across flat position rod type (without clamp arm)



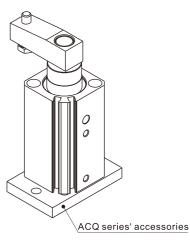


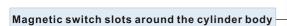
Be used on welding fixfure

It can be used on welding fixfure, the QPQ surface treatment prevent piston rod damage by welding slag; better than chrome plated piston rod.

Better commonness

The mounting dimension of body is the same as ACQ series, can use ACQ series' accessories.





There are magnetic switch slots around the cylinder body convenient to install inducting switch.

Criteria for selection: Cylinder thrust

| 1.1 - 24 | Minima | |
|----------|--------|------|
| Unit: | Newton | (VI) |

| Bore | Rod | A atima tuma | | | Oper | ating pi | ressure | (MPa) | | |
|-------|------|--------------|-------|-------|-------|----------|---------|--------|--------|--------|
| size | size | Acting type | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 |
| 12 | 6 | IN(Clamp) | 8.5 | 17.0 | 25.4 | 33.9 | 42.4 | 50.9 | 59.4 | 67.9 |
| 12 0 | | OUT(Release) | 11.3 | 22.6 | 33.9 | 45.2 | 56.5 | 67.9 | 79.2 | 90.4 |
| 16 | 8 | IN(Clamp) | 15.1 | 30.2 | 45.2 | 60.3 | 75.4 | 90.5 | 105.6 | 120.6 |
| 16 6 | | OUT(Release) | 20.1 | 40.2 | 60.3 | 80.4 | 100.5 | 120.6 | 140.7 | 160.8 |
| 20 | 12 | IN(Clamp) | 20.1 | 40.2 | 60.3 | 80.4 | 100.5 | 120.6 | 140.7 | 160.8 |
| 20 | 12 | OUT(Release) | 31.4 | 62.8 | 94.2 | 125.7 | 157.1 | 188.5 | 219.9 | 251.3 |
| 25 | 12 | IN(Clamp) | 37.8 | 75.6 | 113.3 | 151.1 | 188.9 | 226.7 | 264.4 | 302.2 |
| 25 | 12 | OUT(Release) | 49.1 | 98.2 | 147.3 | 196.3 | 245.4 | 294.5 | 343.6 | 392.7 |
| 32 | 16 | IN(Clamp) | 60.3 | 120.6 | 181.0 | 241.3 | 301.6 | 361.9 | 422.2 | 482.5 |
| 32 | 10 | OUT(Release) | 80.4 | 160.8 | 241.3 | 321.7 | 402.1 | 482.5 | 563.0 | 643.4 |
| 40 | 16 | IN(Clamp) | 105.6 | 211.1 | 316.7 | 422.2 | 527.8 | 633.3 | 738.9 | 844.5 |
| 40 | 16 | OUT(Release) | 125.7 | 251.3 | 377.0 | 502.7 | 628.3 | 754.0 | 879.6 | 1005.3 |
| E0 | 20 | IN(Clamp) | 164.9 | 329.9 | 494.8 | 659.7 | 824.7 | 989.6 | 1154.5 | 1319.5 |
| 50 20 | | OUT(Release) | 196.3 | 392.7 | 589.0 | 785.4 | 981.7 | 1178.1 | 1374.4 | 1570.8 |
| 63 | 20 | IN(Clamp) | 280.3 | 560.6 | 840.9 | 1121.2 | 1401.5 | 1681.9 | 1962.2 | 2242.5 |
| 03 | 20 | OUT(Release) | 311.7 | 623.4 | 935.2 | 1246.9 | 1558.6 | 1870.3 | 2182.1 | 2493.8 |

Installation and application



- 1. Dirty substances in the pipe must be eliminated before cylinder is connected with pipeline to prevent the entrance of impurities into the cylinder.
- 2. The medium used by cylinder shall be filtered to $40\mu m$ or below.
- 3. Anti-freezing measure shall be adopted under low temperature environment to prevent moisture freezing.
- 4. If the cylinder is dismantled and stored for a long time, please conduct anti-rust treatment to the surface. Anti-dust jam cap shall be added in air inlet and outlet ports.
- 5. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.



Rotary clamp cylinder

QCK Series





Specification

| Bore size(mm) | 12 | 16 | 20 | 25 | 32 | 40 | 50 | 63 | | | |
|----------------------|-------|------------|------------|------------|---------------|----------|-------|-----|--|--|--|
| Acting type | | | | Double | acting | | | | | | |
| Fluid | | Air | (to be fil | ered by | 40µm filt | ter elem | ent) | | | | |
| Operating pressure | | 0. | 15~1.0N | IPa(22~ | 145psi)(| 1.5~10b | ar) | | | | |
| Proof pressure | | | 1.5 | MPa(21 | 5psi)(15 | bar) | | | | | |
| Temperature | | | | -20~ | . 70 ℃ | | | | | | |
| Speed range | | 50~200mm/s | | | | | | | | | |
| Rotation angle | | | | 9 | 0° | | | | | | |
| Repeatability | | | | ± 2 | 2° | | | | | | |
| Rotation direction | | | Т | urn left o | r turn rig | ht | | | | | |
| Rotation stroke(mm) | 7 | .5 | 9 | .5 | 1 | 5 | 1 | 19 | | | |
| Clamping stroke (mm) | 10 20 | | 10 20 3 | 0 | | 10 20 | 30 50 | | | | |
| Stroke tolerance | | | | +1.0 | | | | | | | |
| Cushion type | | | | Bun | nper | | | | | | |
| Port size [Note1] | | M5 | ×0.8 | | 1/ | '8" | 1. | /4" | | | |

[Note1]G thread is available.

Add) QCK series are all attached with magnet,

please refer to Page 519 for the specific content of sensor switch.

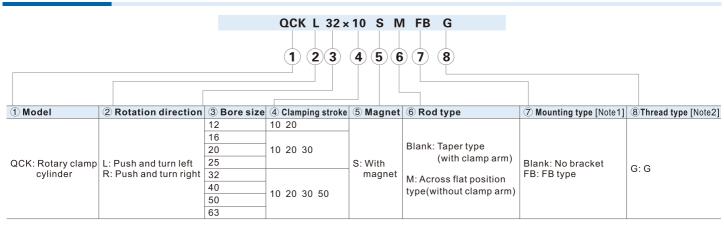
Symbol



Product feature

- 1. It can be used on welding fixfure, the QPQ surface treatment prevent piston rod damage by welding slag; better than chrome plated piston rod.
- The front cover with stainless steel dust scraping ring, can keep the dust and welding slag out, and protect cylinder internal parts.
- 3. The mounting dimension of body is the same as ACQ series, can use ACQ series' accessories.

Ordering code

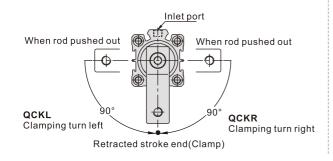


[Note1] Back flange is same as ACQ series (please refer right table), Bore size\Accessories if need front flange, please contact us.

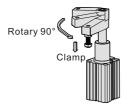
[Note2] When the thread is standard, the code is blank.

| , | Bore size\Accessories | FB | Material | Bore size\Accessories | FB | Material |
|---|-----------------------|-----------|----------|-----------------------|-----------|----------|
| | 12 | F-ACQ12FA | | 32 | F-ACQ32FA | |
| | 16 | F-ACQ16FA | Aluminum | 40 | F-ACQ40FA | Aluminum |
| | 20 | F-ACQ20FA | alloy | 50 | F-ACQ50FA | alloy |
| | 25 | F-ACQ25FA | | 63 | F-ACQ63FA | |

The definition of rotation direction and angle

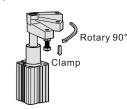


Levorotatory(QCKL): When the piston of cylinder moves downward, the swivel arms moves anticlockwise, this is called levorotatory.



The order code is L

Dextrorotary(QCKR): When the piston of cylinder moves downward, the swivel arms moves clockwise. this is called dextrorotary.



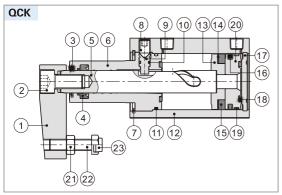
The order code is R





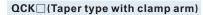
QCK Series

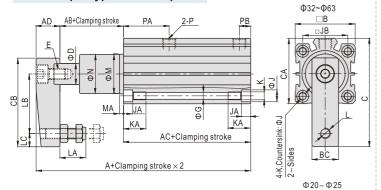
Inner structure and material of major parts



| NO. | Item | Material | NO. | Item | Material |
|-----|---------------------|-------------------------|-----|-------------------|----------------------------------|
| 1 | Rocker | Carbon steel | 14 | Magnet washer | NBR |
| 2 | Screw | Carbon steel | | | Sintered metal |
| 3 | Dust scraping | Νο(Φ12, Φ16) | 15 | Magnet | (Neodymium-iron-boron(Φ12~Φ25) |
| 3 | ring | Stainless steel(Others) | | | Plastic(Others) |
| 4 | Front cover packing | NBR | 16 | Piston seal | NBR |
| 5 | Piston rod | Scr440 | 17 | Back cover | Aluminum alloy |
| 6 | Front cover | Aluminum alloy | 18 | Bumper | TPU(Φ12~Φ25)\NBR(Others) |
| 7 | C Clip | Spring steel | 19 | 11/00 = = = = = = | Νο(Φ12~Φ32) |
| 8 | Screw | Carbon steel | 19 | Wear ring | Wear resistant material (Others) |
| 9 | Operating screw | SCr440 | 20 | Piston | Brass(Φ12, Φ16) |
| 10 | O-ring | NBR | | | Aluminum alloy(Others) |
| 11 | O-ring | NBR | 21 | Screw | Carbon steel |
| 12 | Body | Aluminum alloy | 22 | Fixing screw | Carbon steel |
| 13 | Magnet holder | Brass(Φ12, Φ16) | 23 | Bumper | PTFE(Φ12~Φ40)\POM(Others) |
| 10 | agot noidor | Aluminum alloy(Others) | | | |

Dimensions





2-K,Countersink: ΦJ

2-K, Countersink: ФJ

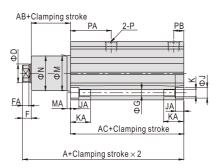
Ф12 Ф16

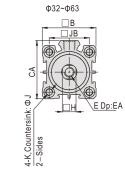
| Bore size\Item | Α | AB | AC | AD | В | вс | С | CA | СВ | D |
|----------------|-----|------|------|------|----|------|-------|------|----|----|
| 12 | 55 | 10.5 | 35.5 | 9 | 25 | 9 | 36.5 | _ | 29 | 6 |
| 16 | 59 | 10.5 | 35.5 | 13 | 29 | 11 | 44.5 | _ | 36 | 8 |
| 20 | 86 | 8 | 62 | 16 | 36 | 16 | 60 | - | 51 | 12 |
| 25 | 87 | 8 | 63 | 16 | 40 | 16 | 62 | _ | 51 | 12 |
| 32 | 108 | 17.5 | 71.5 | 19 | 45 | 19 | 82 | 49.5 | 67 | 16 |
| 40 | 109 | 25 | 65 | 19 | 53 | 19 | 85.5 | 57 | 67 | 16 |
| 50 | 133 | 31 | 76.5 | 25.5 | 64 | 25.5 | 114 | 71 | 88 | 20 |
| 63 | 136 | 30.5 | 80 | 25.5 | 77 | 25.5 | 120.5 | 84 | 88 | 20 |

| Bore size\Item | Е | G | J | JA | JB | JC | K |
|----------------|----------|-----|------|-----|------|----|---------|
| 12 | M3×0.5 | 3.3 | 6 | 3.5 | 15.5 | 22 | M4×0.7 |
| 16 | M5×0.8 | 3.3 | 6 | 3.5 | 20 | 28 | M4×0.7 |
| 20 | M8×1.25 | 5 | 9 | 5.5 | 25.5 | 36 | M6×1.0 |
| 25 | M8×1.25 | 5 | 9 | 5.5 | 28 | 40 | M6×1.0 |
| 32 | M10×1.5 | 5 | 9 | 5.5 | 34 | _ | M6×1.0 |
| 40 | M10×1.5 | 5 | 9 | 5.5 | 40 | _ | M6×1.0 |
| 50 | M12×1.75 | 6.5 | 10.5 | 6.5 | 50 | _ | M8×1.25 |
| 63 | M12×1.75 | 8.5 | 14 | 9 | 60 | _ | M10×1.5 |

| Bore size\Item | KA | L | LA | LB | LC | M | MA | N | Р | PA | РΒ |
|----------------|------|---------|-----------|----|----|----|-----|------|--------|------|------|
| 12 | 11 | M4×0.7 | 7~13 | 20 | 4 | 11 | 3 | 10.8 | M5×0.8 | 13.5 | 5.5 |
| 16 | 11 | M4×0.7 | 7~13 | 25 | 5 | 14 | 3 | 13.8 | M5×0.8 | 15 | 5.5 |
| 20 | 17 | M6×1.0 | 9.5~20.5 | 35 | 7 | 18 | 3 | 17.8 | M5×0.8 | 30 | 6 |
| 25 | 17 | M6×1.0 | 9.5~20.5 | 35 | 7 | 23 | 6 | 22.5 | M5×0.8 | 30 | 7 |
| 32 | 17 | M8×1.25 | 13.5~25.5 | 45 | 10 | 30 | 7 | 29.5 | 1/8" | 34.5 | 8.5 |
| 40 | 17 | M8×1.25 | 13.5~25.5 | 45 | 10 | 30 | 3 | 29.5 | 1/8" | 26.5 | 9 |
| 50 | 22 | M10×1.5 | 14.5~30 | 65 | 10 | 37 | 3.5 | 36.5 | 1/4" | 34 | 11.5 |
| 63 | 28.5 | M10×1.5 | 14.5~30 | 65 | 10 | 48 | 3.5 | 47.5 | 1/4" | 34.5 | 11.5 |

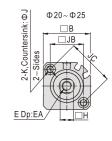
QCK M(Across flat position type without clamp arm)





| Bore size\Item | Α | AB | AC | В | CA | D | F | FA |
|----------------|------|------|------|----|------|----|-----|-----|
| 12 | 48 | 9.5 | 35.5 | 25 | - | 6 | 3 | 2.5 |
| 16 | 48 | 9.5 | 35.5 | 29 | _ | 8 | 3 | 2.5 |
| 20 | 72.5 | 6.5 | 62 | 36 | _ | 12 | 4 | 3 |
| 25 | 73.5 | 6.5 | 63 | 40 | _ | 12 | 4 | 3 |
| 32 | 93.5 | 15.5 | 71.5 | 45 | 49.5 | 16 | 6.5 | 5.5 |
| 40 | 94.5 | 23 | 65 | 53 | 57 | 16 | 6.5 | 5.5 |
| 50 | 112 | 28 | 76.5 | 64 | 71 | 20 | 7.5 | 5.5 |
| 63 | 115 | 27.5 | 80 | 77 | 84 | 20 | 7.5 | 5.5 |

| 50 | 112 | 28 | 76.5 | 64 | 71 | 20 | 7.5 | 5.5 |
|----------------|-----|------|-------|----|-----|-----|-----|-----|
| 63 | 115 | 27.5 | 80 | 77 | 84 | 20 | 7.5 | 5.5 |
| | | | | | | | | |
| Bore size\Item | Н | - 1 | E | EA | ۱ G | | J | JA |
| 12 | 5 | М3 | ×0.5 | 6 | 3.3 | 6 | 3 | 3.5 |
| 16 | 7 | M5 | ×0.8 | 7 | 3.3 | 1 6 | 3 | 3.5 |
| 20 | 10 | M8× | 1.25 | 13 | 5 | (| 9 | 5.5 |
| 25 | 10 | M8× | 1.25 | 13 | 5 | 6 |) | 5.5 |
| 32 | 14 | M10 | ×1.5 | 15 | 5 5 | 6 | 9 | 5.5 |
| 40 | 14 | M10 | ×1.5 | 15 | 5 5 | 6 | 9 | 5.5 |
| 50 | 17 | M12 | ×1.75 | 20 | 6.5 | 10 | .5 | 6.5 |
| 63 | 17 | M12 | ×1.75 | 20 | 8.5 | 1 | 4 | 9 |



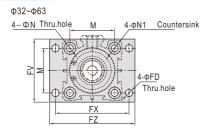
| Bore size\Item | JB | JC | K | KA | M | MA | N | Р | PA | РВ |
|----------------|------|----|---------|------|----|-----|------|--------|------|------|
| 12 | 15.5 | 22 | M4×0.7 | 11 | 11 | 3 | 10.8 | M5×0.8 | 13.5 | 5.5 |
| 16 | 20 | 28 | M4×0.7 | 11 | 14 | 3 | 13.8 | M5×0.8 | 15 | 5.5 |
| 20 | 25.5 | 36 | M6×1.0 | 17 | 18 | 3 | 17.8 | M5×0.8 | 30 | 6 |
| 25 | 28 | 40 | M6×1.0 | 17 | 23 | 6 | 22.5 | M5×0.8 | 30 | 7 |
| 32 | 34 | _ | M6×1.0 | 17 | 30 | 7 | 29.5 | 1/8" | 34.5 | 8.5 |
| 40 | 40 | - | M6×1.0 | 17 | 30 | 3 | 29.5 | 1/8" | 26.5 | 9 |
| 50 | 50 | _ | M8×1.25 | 22 | 37 | 3.5 | 36.5 | 1/4" | 34 | 11.5 |
| 63 | 60 | _ | M10×1.5 | 28.5 | 48 | 3.5 | 47.5 | 1/4" | 34.5 | 11.5 |

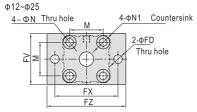
Rotary clamp cylinder

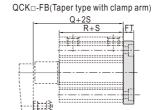
AITTAC

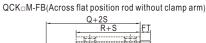
QCK Series

Q□K-FB(With flange)







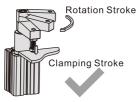


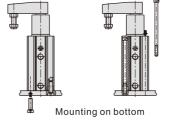
| Q+2S |
|--------------|
| R+S FT |
| |
| <u> </u> |
| |
| 8 |
| L4 |
| |
| |

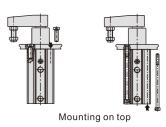
| Bore size\Item | R | Q(QCK□) | Q(QCK□M) | M | N | N1 | FD | FT | FV | FX | FZ |
|----------------|------|---------|----------|------|------|------|-----|-----|----|----|-----|
| 12 | 35.5 | 46 | 48 | 15.5 | 4.5 | 7.5 | 4.5 | 5.5 | 25 | 45 | 55 |
| 16 | 35.5 | 46 | 48 | 20 | 4.5 | 7.5 | 4.5 | 5.5 | 30 | 45 | 55 |
| 20 | 62 | 70 | 72.5 | 25.5 | 6.5 | 10.5 | 6.5 | 8 | 39 | 48 | 60 |
| 25 | 63 | 71 | 73.5 | 28 | 6.5 | 10.5 | 6.5 | 8 | 42 | 52 | 64 |
| 32 | 71.5 | 89 | 93.5 | 34 | 6.5 | 10.5 | 5.5 | 8 | 48 | 56 | 65 |
| 40 | 65 | 90 | 94.5 | 40 | 6.5 | 10.5 | 5.5 | 8 | 54 | 62 | 72 |
| 50 | 76.5 | 107.5 | 112 | 50 | 8.5 | 13.5 | 6.5 | 9 | 67 | 76 | 89 |
| 63 | 80 | 110.5 | 115 | 60 | 10.5 | 16.5 | 9 | 9 | 80 | 92 | 108 |

Installation and operation

- 1. To insure the life-span of cylinder and jig, please use flow control valve to control the speed of cylinder.
- 2. The method of installation are mounted by flange on top or bottom.
- 3. Befor the cylinder is connected to pipeline sundries in the pipe must be eliminated, or may cause leakage.
- 4. Please clean the piston–rod and dust scraping ring to protect the cylinder.
- 5. The cylinder using normal magnet ring can use the same sensor as ACQ series. For the cylinder using strong magnet ring we suggest using AirTAC's CS1-69AM sensor.
- Because the rotary force is strong when the cylinder's acting, we suggest using flow control valve to control the speed to protect cylinder.
- 7. Please install the cylinder following the right diagram.
- 8. The installation method as the diagram below is wrong, and will injure the cylinder and shorten the cylinder life.



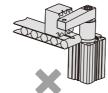




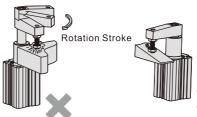
Only can clamping in clamping stroke.



Don't installed horizontally



Don't exert horizontally load or force

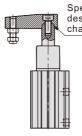


Please don't clamp when rotating.

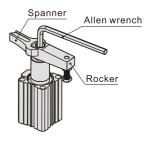


Do not more the workpiece when clamped

- 9. Rocker
- 9.1) The design of rocker can keep it stable and can change direction by customer.
- 9.2) Please follow the diagram below on right side to assemble/disassemble the rocker by spanner and allen wrench; don't hold the body to assemble/disassemble rocker, or will damage the cylinder.
- 9.3) If need customize rocker, please contact us.



Special conical surface locked design can keep it stable and can change direction by customer.





Rotary clamp cylinder



arm: I

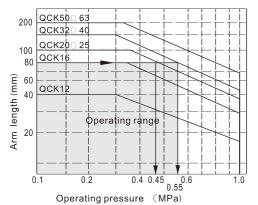
Jig mass:m

QCK Series

How to select product

- 1. When arms are to be made separately, their length and weight should be within the following range.
- 2. Allowable bending moment:

Use the arm length and operating pressure within graph(1) for allowable bending moment loaded piston rod.

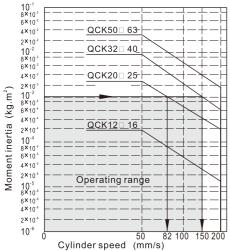


Example: When arm length is 80mm, pressure should be

QCK20/25:0.45MPa QCK32/40:0.55MPa

3. Moment of inertia:

When the arm is long and heavy, damage of internal parts may be caused due to inertia. Use the inertia moment and cylinder speed within graph(2) based on arm requirments.



Example: When arm's moment of inertia is 10⁻³Kg·m², cylinder

speed should be less than QCK20/25:82mm/s

QCK32/40:150mm/s

Note) The average speed of piston=the highest speed of piston/1.6

4. Moment of inertia of cylinder's arm when rotating based on its rotary axis, shown in graph(3).

| Model | Moment of inertia(Kg·m²) |
|----------|--------------------------|
| QCK12 | 3.555×10^{-6} |
| QCK16 | 1.053×10 ⁻⁵ |
| QCK20\25 | 5.257×10 ⁻⁵ |
| QCK32\40 | 1.653×10 ⁻⁴ |
| QCK50\63 | 7.387×10^{-4} |

- - 5.1) Moment of inertia of arm (I1): Refer to the graph(3) after he cylinder bore diameter is determined.
 - 5.2) Moment of inertia of jig (I2): According to shape of the jig and the next item 6 "Calculation for moment of inertia", pick out a proper formula for calculation. The jig shown on the right graph is a cylinder ,its formula $_{\mbox{jig: I}_2}$ of moment of inertia is:

 $I_2 = (m_2 * D * D)/8 + m_2 * L * L$

When QCK32 is selected: L=0.045m(arm length);

If D=0.04m $m_2=0.4kg$

From graph(3): $I_1 = 1.653 \times 10^{-4} (\text{Kg} \cdot \text{m}^2)$

By Calculation : $I_2 = (m_2 * D * D)/8 + m_2 * L * L = \square 0.4 * 0.04 * 0.04)/8 + 0.4 * 0.045 * 0.045$ =8.9×10-4 (Kg·m²)

Total value: $I=I_1+I_2=10.553\times10^{-4}=1.0553\times10^{-3}(Kg\cdot m^2)$

According to graph(2), the highest speed of the cylinder should be less than 150 mm/s; According to graph(1), it can be used under a pressure of 0.9Mpa. The average speed of piston=the highest speed of piston/1.6=94 mm/s.

| Diagram | Calculation formula of moment of inerti |
|--|---|
| 1. Thin bar Position of rotary axis: Vertical to the bar and through the end | $I = \frac{m_1 a_1^2 + m_2 a_2^2}{3}$ |
| 2. Thin bar Position of rotary axis: Vertical to the bar and through the center of gravity | $I = \frac{ma^2}{12}$ |
| 3. Load at the end of lever arm a, a, m, | $I = m_{1} \times \frac{a_{1}^{2}}{3} + m_{2} \times a_{2}^{2} + k$ $k = m_{2} \times \frac{2r^{2}}{5}$ |
| 4. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Parallel to side b and through the center of gravity | $I = \frac{ma^2}{12}$ |
| 5. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Vertica to the plate and through the end | $I = m_1 \times \frac{4a_1^2 + b^2}{12} + m_2 \times \frac{4a_2^2 + b^2}{12}$ |
| 6. Thin rectangular plate (Rectangular parallelepiped) Position of rotary axis: Through the center of gravity and vertical to the plate(Same as also thickrectanglaur plate) | $I = \frac{ma^2 + mb^2}{12}$ |